Improving Christofides' Algorithm for the *s*-*t* Path TSP

Hyung-Chan An

Joint work with Bobby Kleinberg and David Shmoys

Metric TSP

- Metric (circuit) TSP
 - Given a weighted graph G = (V, E) (c : E → ℝ₊), find a minimum Hamiltonian circuit
 - Triangle inequality holds
 - Christofides (1976) gave a 3/2-approximation algorithm



Figure from [Dantzig, Fulkerson, Johnson 1954]

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 - Triangle inequality holds
 - Christofides (1976) gave a 3/2-approximation algorithm
 - No better performance guarantee known



Figure from [Dantzig, Fulkerson, Johnson 1954]

Metric s-t Path TSP

- Metric s-t path TSP
 - Given a weighted graph G = (V, E) (c : E → ℝ₊) with endpoints s, t ∈ V, find a minimum s-t Hamiltonian path
 - Triangle inequality holds
 - Hoogeveen (1991) showed that Christofides' algorithm is a 5/3-approximation algorithm and this bound is tight



Figure from [Dantzig, Fulkerson, Johnson 1954]

Our Main Result

Theorem

Christofides' algorithm can be improved to yield a deterministic ϕ -approximation algorithm for the s-t path TSP for an arbitrary metric, where $\phi = \frac{1+\sqrt{5}}{2}$ is the golden ratio ($\phi < 1.6181$)

Recent Exciting Improvements

Recent improvements for unit-weight graphical metric TSP

- Shortest path metric in an underlying unweighted graph
- Better approximation than Christofides' ([Oveis Gharan, Saberi, Singh 2011], [Mömke, Svensson 2011], [Mucha 2011], [Sebő, Vygen 2012])

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- Techniques can be successfully applied to both variants
- Our algorithm for the s-t path TSP improves Christofides' for an arbitrary metric
 - Can our techniques be extended to the circuit variant?

Hyung-Chan An Improving Christofides' Algorithm for the *s*-*t* Path TSP

- Find minimum span. tree \mathscr{T}_{\min}
- Augment *𝔅*_{min} into a low-cost Eulerian circuit/path
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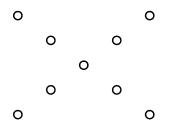
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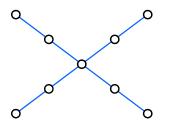
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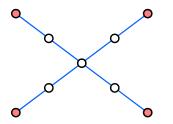
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- ϕ -approx for *s*-*t* path TSP
 - Arbitrary metric
 - Simpler random choice



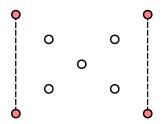
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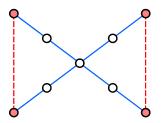
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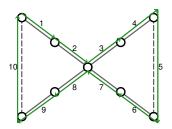
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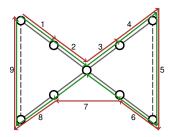
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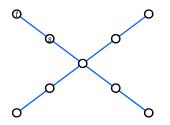
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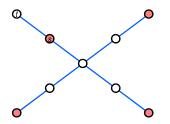
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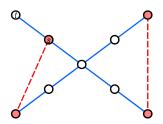
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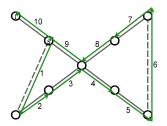
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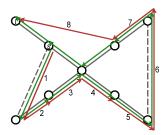
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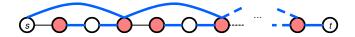


 Unit-weight graphical metric: distance between two vertices defined as shortest distance on this underlying unit-weight graph

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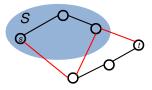
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 Unit-weight graphical metric: distance between two vertices defined as shortest distance on this underlying unit-weight graph

- Held-Karp relaxation
 - $\delta(S)$ for $S \subsetneq V$ denotes the set of edges in cut (S, \overline{S})



• Incidence vector
$$\chi_F$$
 of $F \subset E$ is $(\chi_F)_e := \begin{cases} 1 & \text{if } e \in F \\ 0 & \text{otherwise} \end{cases}$

Held-Karp relaxation

For G = (V, E) and $s, t \in V$,

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- Feasible region of this LP is contained in the ST polytope
- Held-Karp solution can be written as a convex combination of (incidence vectors of) spanning trees
- Can find such a decomposition in polynomial time [Grötschel, Lovász, Schrijver 1981]

Our Algorithm

- Best-of-Many Christofides' Algorithm
 - Compute an optimal solution x* to the Held-Karp relaxation
 - Rewrite x^* as a convex comb. of spanning trees $\mathscr{T}_1, \ldots, \mathscr{T}_k$
 - For each *T_i*:
 - Let T_i be the set of vertices with "wrong" parity of degree:
 i.e., T_i is the set of even-degree endpoints and other odd-degree vertices in S_i
 - Find a minimum perfect matching *M_i* on *T_i*
 - Find an *s*-*t* Eulerian path of $\mathscr{T}_i \cup M_i$
 - Shortcut it into an *s*-*t* Hamiltonian path *H_i*
 - Output the best Hamiltonian path

Randomized Algorithm

- Sampling Christofides' Algorithm
 - Sample \mathscr{T} by choosing \mathscr{T}_i with probability λ_i

 $(\mathbf{x}^* = \sum_{i=1}^k \lambda_i \chi_{\mathscr{T}_i})$

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 Best-of-Many Christofides' Algorithm is ρ-approx. algorithm
- $\Pr[e \in \mathscr{T}] = x_e^*$
 - $\mathsf{E}[c(\mathscr{T})] = \sum_{e \in E} c_e x_e^* = c(x^*)$
 - The rest of the analysis focuses on bounding *c*(*M*)

Polyhedral Characterization of Matchings

 Polyhedral characterization of matchings on *T* (assuming triangle inequality) [Edmonds, Johnson 1973]

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$$\begin{array}{c} \bullet & \bullet \\ \bullet & \bullet \\ \bullet & \bullet \\ \bullet & \bullet \\ \end{array} \begin{array}{c} \sum_{e \in \delta(S)} y_e \geq 1, \quad \forall S \subset V, |S \cap T| \text{ odd} \\ y \in \mathbb{R}_+^E \end{array}$$

 Call a feasible solution a *fractional matching*; its cost upper-bounds c(M)

• Want: a fractional matching y with $E[c(y)] \le \frac{2}{3}c(x^*)$ $x^* :=$ optimal Held-Karp solution

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 for $\alpha = \beta = \frac{1}{3}$

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$$(\text{Matching}) \quad \begin{cases} \sum_{e \in \delta(S)} y_e \geq 1, & \forall S \subset V, |S \cap T| \text{ odd} \\ y \in \mathbb{R}_+^{\mathcal{E}} \end{cases}$$

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LB on *T*-odd *s-t* cut capacities 1

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$$\begin{cases} \sum_{\substack{e \in \delta(\{s\}) \\ e \in \delta(\{v\}) \\ e \in \delta(\{v\}) \\ e \in \delta(S) \\ e \in \delta(S) \\ \sum_{e \in \delta(S)} x_e \ge 1, \\ e \in \delta(S) \\ S = 1, \\ e \in \delta(S) \\ S = 2, \\ e \in \delta(S) \\ 0 \le x_e \le 1 \end{cases} \quad \forall S \subsetneq V, |\{s,t\} \cap S| = 1 \\ \forall S \subsetneq V, |\{s,t\} \cap S| \neq 1, S \neq \emptyset \\ \forall S \subseteq V, |\{s,t\} \cap S| \neq 1, S \neq \emptyset \end{cases}$$

2

y

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 $\chi_{\mathscr{T}}$ x^* yLB on *T*-odd *s-t* cut capacities11LB on nonseparating cut capacities12

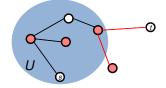
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 $\frac{\chi_{\mathscr{T}}}{2} \frac{x^*}{1}$ LB on *T*-odd *s*-*t* cut capacities LB on nonseparating cut capacities 1

Lemma

An s-t cut (U, \overline{U}) that is odd w.r.t. T (i.e., $|U \cap T|$ is odd) has at least two tree edges in it



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$$\mathsf{E}[c(y)] = \alpha \mathsf{E}[c(\chi_{\mathscr{T}})] + \beta c(x^*) = (\alpha + \beta)c(x^*)$$

•
$$\mathsf{E}[c(H)] \leq \mathsf{E}[c(\mathscr{T})] + \mathsf{E}[c(M)] \leq (1 + \alpha + \beta)c(x^*)$$

Theorem

The given algorithm is a $(1 + \alpha + \beta)$ -approximation algorithm

	$\chi_{\mathscr{T}}$	X *	У
LB on <i>T</i> -odd <i>s</i> - <i>t</i> cut capacities	2	1	$2\alpha + \beta$
LB on nonseparating cut capacities	1	2	$\alpha + 2\beta$

• Perturb α and β

• In particular, decrease α by 2ϵ and increase β by ϵ

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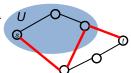
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- $E[c(y)] = (\alpha + \beta)c(x^*)$ decreases by $\epsilon c(x^*)$
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- T-odd s-t cuts with small capacity may become violated
 - If violated, by at most $d := O(\epsilon)$

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Definition

For $0 < \tau \le 1$, a τ -narrow cut (U, \overline{U}) is an s-t cut with $\sum_{e \in \delta(U)} x_e^* < 1 + \tau$



 τ-narrow cuts may be violated when they are T-odd

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Proof.

• Expected number of tree edges in the cut is $< 1 + \tau$: $\sum_{e \in \delta(U)} \Pr[e \in \mathscr{T}] = \sum_{e \in \delta(U)} x_e^* < 1 + \tau$

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$$\Pr[e \in \mathscr{T}] = x_e^*$$

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- Expected number of tree edges in the cut is $< 1 + \tau$: $\sum_{e \in \delta(U)} \Pr[e \in \mathscr{T}] = \sum_{e \in \delta(U)} x_e^* < 1 + \tau$
- (U, \overline{U}) has at least one tree edge in it
- If (U, \overline{U}) is odd w.r.t. T, it must have another tree edge in it

•
$$\Pr[e \in \mathscr{T}] = x_e^*$$

Lemma

An s-t cut (U, \overline{U}) that is odd w.r.t. T (i.e., $|U \cap T|$ is odd) has at least two tree edges in it

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$$\mathbf{y} := \alpha \chi_{\mathscr{T}} + \beta \mathbf{x}^* + \mathbf{r}$$

 For each e, if e is in a τ-narrow cut that is odd w.r.t. T, set r_e := dx^{*}_e

Claim y is a fractional matching

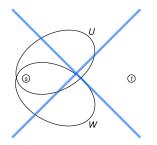
Claim $E[c(r)] \leq d\tau c(x^*)$

τ-narrow cuts are not disjoint

• τ -narrow cuts are not disjoint, but "almost" disjoint

Lemma

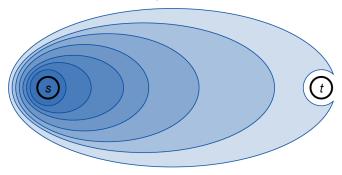
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Lemma

Each τ -narrow cut has a "representative" edge set of capacity $\geq 1 - \frac{\tau}{2}$, and they are mutually disjoint

The Main Result

Theorem

Best-of-many Christofides' algorithm is a deterministic ϕ -approximation algorithm for the s-t path TSP for the general metric, where $\phi = \frac{1+\sqrt{5}}{2} < 1.6181$ is the golden ratio

Open Questions

- Circuit TSP
 - Is there a better than 3/2-approximation algorithm?
 - Do our techniques extend to the circuit TSP?

Thank you.