## Improving Christofides' Algorithm for the s-t Path TSP

Hyung-Chan An

Joint work with Bobby Kleinberg and David Shmoys

## Metric TSP

- Metric (circuit) TSP
- Given a weighted graph $G=(V, E)\left(c: E \rightarrow \mathbb{R}_{+}\right)$, find a minimum Hamiltonian circuit
- Triangle inequality holds
- Christofides (1976) gave a 3/2-approximation algorithm


Figure from [Dantzig, Fulkerson, Johnson 1954]

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- Triangle inequality holds
- Christofides (1976) gave a 3/2-approximation algorithm
- No better performance guarantee known



## Metric s-t Path TSP

- Metric s-t path TSP
- Given a weighted graph $G=(V, E)\left(c: E \rightarrow \mathbb{R}_{+}\right)$with endpoints $s, t \in V$, find a minimum $s$ - $t$ Hamiltonian path
- Triangle inequality holds
- Hoogeveen (1991) showed that Christofides' algorithm is a $5 / 3$-approximation algorithm and this bound is tight


Figure from [Dantzig, Fulkerson, Johnson 1954]

## Our Main Result

## Theorem

Christofides' algorithm can be improved to yield a deterministic $\phi$-approximation algorithm for the s-t path TSP for an arbitrary metric, where $\phi=\frac{1+\sqrt{5}}{2}$ is the golden ratio $(\phi<1.6181)$

## Recent Exciting Improvements

- Recent improvements for unit-weight graphical metric TSP
- Shortest path metric in an underlying unweighted graph
- Better approximation than Christofides' ([Oveis Gharan, Saberi, Singh 2011], [Mömke, Svensson 2011], [Mucha 2011], [Sebő, Vygen 2012])


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- Better approximation than Christofides' ([Oveis Gharan, Saberi, Singh 2011], [Mömke, Svensson 2011], [Mucha 2011], [Sebő, Vygen 2012])
- Techniques can be successfully applied to both variants
- Our algorithm for the $s$ - $t$ path TSP improves Christofides' for an arbitrary metric
- Can our techniques be extended to the circuit variant?


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- Proved for unit-weight graphical metric
- $\phi$-approx for $s$ - $t$ path TSP
- Arbitrary metric
- Simpler random choice


## Christofides’ Algorithm

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0

$$
\begin{array}{llll} 
& & 0 \\
0 & & 0 & \\
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- Shortcut it into a Hamiltonian circuit $H$



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## Path-variant Christofides’ algorithm

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- 5/3-approximation algorithm [Hoogeveen 1991]
- This bound is tight

- Unit-weight graphical metric: distance between two vertices defined as shortest distance on this underlying unit-weight graph


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## Held-Karp Relaxation

- Held-Karp relaxation
- $\delta(S)$ for $S \subsetneq V$ denotes the set of edges in cut $(S, \bar{S})$

- Incidence vector $\chi_{F}$ of $F \subset E$ is $\left(\chi_{F}\right)_{e}:= \begin{cases}1 & \text { if } e \in F \\ 0 & \text { otherwise }\end{cases}$


## Held-Karp Relaxation

- Held-Karp relaxation

For $G=(V, E)$ and $s, t \in V$,

$$
\begin{array}{ll} 
\begin{cases}\sum_{e \in \delta(\{s\})} x_{e}=\sum_{e \in \delta(\{t\})} x_{e}=1 & \\
\sum_{e \in \delta(\{v\})} x_{e}=2, & \forall v \in V \backslash\{s, t\} \\
\sum_{e \in \delta(S)} x_{e} \geq 1, & \forall S \subsetneq V,|\{s, t\} \cap S|=1 \\
\sum_{e \in \delta(S)} x_{e} \geq 2, & \forall S \subsetneq V,|\{s, t\} \cap S| \neq 1, S \neq \emptyset \\
0 \leq x_{e} \leq 1 & \forall e \in E \\
x \in \mathbb{R}^{E}\end{cases}
\end{array}
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- Polynomial-time solvable
- Feasible region of this LP is contained in the ST polytope


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## Held-Karp Relaxation

- Polynomial-time solvable
- Feasible region of this LP is contained in the ST polytope
- Held-Karp solution can be written as a convex combination of (incidence vectors of) spanning trees
- Can find such a decomposition in polynomial time [Grötschel, Lovász, Schrijver 1981]


## Our Algorithm

- Best-of-Many Christofides' Algorithm
- Compute an optimal solution $x^{*}$ to the Held-Karp relaxation
- Rewrite $x^{*}$ as a convex comb. of spanning trees $\mathscr{T}_{1}, \ldots, \mathscr{T}_{k}$
- For each $\mathscr{T}_{1}$ :
- Let $T_{i}$ be the set of vertices with "wrong" parity of degree: i.e., $T_{i}$ is the set of even-degree endpoints and other odd-degree vertices in $\mathscr{T}_{i}$
- Find a minimum perfect matching $M_{i}$ on $T_{i}$
- Find an s-t Eulerian path of $\mathscr{T}_{i} \cup M_{i}$
- Shortcut it into an s-t Hamiltonian path $H_{i}$
- Output the best Hamiltonian path


## Randomized Algorithm

- Sampling Christofides' Algorithm
- Sample $\mathscr{T}$ by choosing $\mathscr{T}_{i}$ with probability $\lambda_{i}$ $\left(x^{*}=\sum_{i=1}^{k} \lambda_{i} \chi_{\mathscr{T}_{i}}\right)$


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- $\mathrm{E}[c(H)] \leq \rho \cdot \mathrm{OPT} \Longrightarrow$

Best-of-Many Christofides' Algorithm is $\rho$-approx. algorithm

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- $\operatorname{Pr}[e \in \mathscr{T}]=x_{e}^{*}$
- $\mathrm{E}[c(\mathscr{T})]=\sum_{e \in E} c_{e} x_{e}^{*}=c\left(x^{*}\right)$
- The rest of the analysis focuses on bounding $c(M)$


## Polyhedral Characterization of Matchings

- Polyhedral characterization of matchings on $T$ (assuming triangle inequality)
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- Call a feasible solution a fractional matching; its cost upper-bounds $c(M)$


## Proof of 5/3-approximation

- Want: a fractional matching $y$ with $\mathrm{E}[c(y)] \leq \frac{2}{3} c\left(x^{*}\right)$ $x^{*}:=$ optimal Held-Karp solution


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(Matching) $\left\{\begin{array}{l}\sum_{e \in \delta(S)} y_{e} \geq 1, \quad \forall S \subset V,|S \cap T| \text { odd } \\ y \in \mathbb{R}_{+}^{E}\end{array}\right.$


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|  | $\chi_{\mathscr{F}}$ | $x^{*}$ | $y$ |
| :---: | :---: | :---: | :---: |
| LB on $T$-odd $s$ - $t$ cut capacities | 1 |  |  |
| LB on nonseparating cut capacities | 2 |  |  |



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## Lemma

An s-t cut $(U, \bar{U})$ that is odd w.r.t. $T$ (i.e., $|U \cap T|$ is odd) has at least two tree edges in it


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- $\mathrm{E}[c(y)]=\alpha \mathrm{E}\left[\boldsymbol{c}\left(\chi_{\mathscr{T}}\right)\right]+\beta \boldsymbol{c}\left(x^{*}\right)=(\alpha+\beta) c\left(x^{*}\right)$
- $\mathrm{E}[c(H)] \leq \mathrm{E}[c(\mathscr{T})]+\mathrm{E}[c(M)] \leq(1+\alpha+\beta) c\left(x^{*}\right)$

Theorem
The given algorithm is a $(1+\alpha+\beta)$-approximation algorithm

## Improvement upon 5/3



- Perturb $\alpha$ and $\beta$
- In particular, decrease $\alpha$ by $2 \epsilon$ and increase $\beta$ by $\epsilon$


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- In particular, decrease $\alpha$ by $2 \epsilon$ and increase $\beta$ by $\epsilon$
- $\mathbf{E}[\boldsymbol{c}(y)]=(\alpha+\beta) \boldsymbol{c}\left(x^{*}\right)$ decreases by $\epsilon \boldsymbol{C}\left(x^{*}\right)$
- $\alpha+2 \beta$ unchanged; nonseparating cuts remain satisfied
- $T$-odd $s$ - $t$ cuts with small capacity may become violated
- If violated, by at most $d:=O(\epsilon)$


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Definition
For $0<\tau \leq 1$, a $\tau$-narrow cut $(U, \bar{U})$ is an s-t cut with $\sum_{e \in \delta(U)} x_{e}^{*}<1+\tau$


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## Proof.

- Expected number of tree edges in the cut is $<1+\tau$ :
$\sum_{e \in \delta(U)} \operatorname{Pr}[e \in \mathscr{T}]=\sum_{e \in \delta(U)} x_{e}^{*}<1+\tau$
- $\operatorname{Pr}[e \in \mathscr{T}]=x_{e}^{*}$


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- $(U, \bar{U})$ has at least one tree edge in it
- If $(U, \bar{U})$ is odd w.r.t. $T$, it must have another tree edge in it
- $\operatorname{Pr}[e \in \mathscr{T}]=x_{e}^{*}$

Lemma
An s-t cut $(U, \bar{U})$ that is odd w.r.t. $T$ (i.e., $|U \cap T|$ is odd) has at least two tree edges in it

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- Suppose edge sets of $\tau$-narrow cuts were disjoint
- $y:=\alpha \chi_{\mathscr{T}}+\beta \boldsymbol{x}^{*}+r$
- For each $e$, if $e$ is in a $\tau$-narrow cut that is odd w.r.t. $T$, set $r_{e}:=d x_{e}^{*}$
Claim $y$ is a fractional matching
Claim $\mathrm{E}[c(r)] \leq d \tau c\left(x^{*}\right)$


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- $\tau$-narrow cuts are not disjoint


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- $\tau$-narrow cuts are not disjoint, but "almost" disjoint

Lemma
$\tau$-narrow cuts do not cross: i.e., for $\tau$-narrow cuts $(U, \bar{U})$ and $(W, \bar{W})$ with $s \in U, W$, either $U \subset W$ or $W \subset U$.

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Lemma
Each $\tau$-narrow cut has a "representative" edge set of capacity
$\geq 1-\frac{\tau}{2}$, and they are mutually disjoint

## The Main Result

## Theorem

Best-of-many Christofides' algorithm is a deterministic $\phi$-approximation algorithm for the s-t path TSP for the general metric, where $\phi=\frac{1+\sqrt{5}}{2}<1.6181$ is the golden ratio

## Open Questions

- Circuit TSP
- Is there a better than $3 / 2$-approximation algorithm?
- Do our techniques extend to the circuit TSP?

Thank you.

